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Limit value of the Nusselt number for particles of different shape

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Abstract

The limit value of the Nusselt number for pure heat conduction was numerically determined for different particle shapes. In the case of nonspherical particles, substantial errors can result in the calculation of the heating time when the Nusselt number of the sphere Nu = 2 is applied and the sieve diameter is used as the characteristic dimension. That a uniform description of the Nusselt number is possible for all considered particle shapes is demonstrated. However, this Nusselt number, determined using the sieve diameter, is then not constant, but depends exponentially on the ratio of the Sauter diameter to the sieve diameter. © 2001 Elsevier Science Ltd. All rights reserved.

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1. Introduction

An idealized spherical shape of the particle is usually assumed when calculating the heat and mass transfer between solid particles and a surrounding fluid. However, to a certain extent the real shape of such particles differs substantially from this ideal shape. Particularly unevenness and edges play a large role in solid particles. By comparison, liquid particles always have an approximately spherical shape due to the surface tension. In the case of solid particles in the um-range, e.g. coal particles or dusts, the heat and mass transfer essentially take place through conduction or diffusion. Due to the small diameter and the low relative velocity to the fluid, the Reynolds number Re approaches zero. If, for example, the sedimentation velocity is assumed to be the relative velocity of the particles, a Reynolds number of Re = 0.08 results for a particle with a diameter d = 100 μ m and a density $\rho = 1300 \text{ kg/m}^3$ in hot air of 1000°C.

Thus the convection part in the Nusselt number equation [1]

$$Nu = 2 + 0.664 Re^{0.5} Pr^{1/3}$$
⁽¹⁾

is smaller than 0.2 and, compared with the minimum limit of Nu = 2 resulting from heat conduction, is negligible. Even in the case of larger particles, higher relative velocity and lower gas temperatures, as a rule the limit value of 2 in comparison with the convection part cannot always be disregarded. The limit value of the Nusselt number for different particle shapes is therefore examined below. The minimum value of the heat flow results from thermal conduction in the infinitely extended fluid. The heat flow \dot{Q} is defined by a heat transfer coefficient α in accordance with

$$Q = \alpha A (\vartheta_{\rm W} - \vartheta_{\infty}) \tag{2}$$

with A is the surface area of the particle, ϑ_W the surface temperature of the particle and ϑ_∞ is the ambient temperature.

This value can be analytically determined for the sphere and the spheroid with the limit case circular disk. For the circular cylinder, the cube and two touching spheres approximate solutions are known from the field of electrostatics. The steady-state temperature field

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Nomenclature		Greek symbols			
Nomer a A c d L N Nu Pr ġ Q Re	nclaturethermal diffusivitysurface areaspecific heat capacitydiameterlengthnumber of wavesNusselt number, $\alpha d_{ch}/\lambda$ Prandtl number, v/a heat fluxheat flowReynolds number, wd/v	Greek sym. lpha hea λ then ϑ term v kin. Θ dim $(\vartheta - \rho$ den Subscripts a out A surf ch cha	bols t transfer coefficient rmal conductivity perature ematic viscosity nensionless temperature, $-\vartheta_{\infty})/(\vartheta_{W} - \vartheta_{\infty})$ isity er face racteristic		
V W X X Y Y Z Z	volume velocity coordinate dimensionless coordinate, x/d_{ch} coordinate dimensionless coordinate, y/d_{ch} coordinate dimensionless coordinate, z/d_{ch}	mmeattimSSauVvolWwal0stan ∞ at a	an e ater ume 1 t value a great distance, in infinity		

around the body is then analogous to the electrostatic field around an electrically charged body. A coefficient $\alpha A/\lambda$ usually results as solution. In literature, this quantity is also denoted as shape coefficient [2] or conductance [3]. Table 1 specifies the value of the shape coefficient for the bodies named above.

In the case of the sphere, the shape coefficient is dependent on the diameter d, while in the case of the spheroid and the circular cylinder it additionally depends on the length to diameter ratio L/d. A separate function is obtained for each geometry. Thus a generally valid presentation, e.g. with a Nusselt number, is impossible. The difficulty is defining a characteristic di-

mension. The objective of this study is to find a universally applicable formulation for different geometries. What is more, it addresses the question of which dimension is crucial for the heat transfer in particular.

2. Characteristic dimension for the Nusselt number

The subsequent observations are restricted to axisymmetric bodies. The following dimensions can be selected as characteristic for these bodies:

- diameter, *d*;
- length, L;

Table	1					
Shape	coefficient	$\alpha A/\lambda$ for	or particle	s in a	stagnant	medium

Particle shape	Shape coefficient $\alpha A/\lambda$	Refs.				
Sphere	$2\pi d$	[2-4]				
Spheroid		[2-4]				
Oblate $(L/d < 1)$	$2\pi d\sqrt{1-\left(L/d ight)^2}$					
	$\arccos(L/d)$					
Prolate $(L/d > 1)$	$\frac{2\pi d\sqrt{(L/d)^2 - 1}}{\ln\left(L/d\right) + \sqrt{(L/d)^2 - 1}}$					
	$\operatorname{Im}\left(L/a + \sqrt{(L/a)} - 1\right)$					
Circular disk $(L/d = 0)$	4d	[2-4]				
Circular cylinder $(0 \le L/d \le 8)$	$[8+6.95(L/d)^{0.76}]d/2$	[3,5]				
Cube (edge <i>a</i>)	0.656 4πa	[3]				
Two touching spheres of equal size	$(2\ln 2)(2\pi d)$	[3]				

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Fig. 1. Characteristic dimensions using a cylinder with L/d = 2 as an example.

- surface diameter, $d_A = \sqrt{A/\pi}$;
- volume diameter, $d_{\rm V} = \sqrt[3]{\frac{6}{\pi}V}$;
- Sauter diameter, $d_{\rm S} = 6V/A$;
- mean diameter, $d_{\rm m} = (d + L)/2$.

Only in the case of the sphere, these dimensions are equally large and correspond to the diameter. Using a cylinder with L/d = 2 as an example, Fig. 1 compares the characteristic dimensions with each other. The diameter d of the particle, which can be determined by means of sieving, is the value most easily determined metrologically. The Sauter diameter can be calculated from the specific surface area A/V which can be measured by means of the gas adsorption method of Brunauer, Emmett and Teller (BET method). For porous materials however, the measured value is not equivalent to the outer surface area of the particle. The diameter $d_{\rm V}$ can be determined by means of the electric sensing zone method (Coulter Counter). However, for bodies with concave surface parts, the measured value does not correspond to the body volume but to the enveloping volume. The diameter d_A can be determined from the

combination of the measured values from the Coulter Counter and BET. The mean diameter can be approximately determined by means of optical particle counters and the length can only be determined from direct measurement by means of a microscope. The influence of d_{ch} on the value of the Nusselt number is compared using the spheroid as an example. If in the definition equation of the Nusselt number

$$Nu = \frac{\alpha d_{\rm ch}}{\lambda},\tag{3}$$

the characteristic diameter d_{ch} is replaced by one of the aforementioned six diameters, then

$$Nu = \frac{\alpha A}{\lambda} \frac{d_{\rm ch}}{A} \tag{4}$$

is obtained using the shape coefficient $\alpha A/\lambda$ from Table 1.

The Nusselt numbers resulting for a spheroid with different length to diameter ratios L/d are plotted in Fig. 2 for the various characteristic dimensions. The smallest influence of the ratio L/d and the smallest difference from the value Nu = 2 of the sphere appear when the volume diameter or the surface diameter are applied. By comparison, a considerable deviation from the value 2 results in the case of the other characteristic dimensions. In the case of the sieve diameter d usually applied as characteristic dimension, the Nusselt number of the sphere Nu = 2 is not suitable for the spheroid. Consequently, it is also unsuitable for other particle shapes. The deviation of the Nusselt numbers in accordance with Fig. 2 from the value 2 still does not express everything about the error when calculating the heating time of real particles. An additional error results from the unknown volume and the unknown surface area of



Fig. 2. Nusselt numbers $Nu(d_{ch})$ for various characteristic dimensions in the case of a spheroid.

the particle, which are necessary for calculating heating time. They are also determined incorrectly if only the sieve diameter is known.

3. Calculation of the heating time

In the case of small particles, a homogeneous temperature distribution in the particle can be assumed (Biot \rightarrow 0). Thus the heating time *t* is calculated from the energy balance

$$\alpha A(\vartheta - \vartheta_{\infty}) = \rho V c \frac{\mathrm{d}\vartheta}{\mathrm{d}t}.$$
(5)

With the initial condition $\vartheta(t=0) = \vartheta_0$ and assuming A, ρ , V to be constant, the following results when the ambient temperature ϑ_{∞} is constant:

$$t = \frac{V}{\alpha A} \rho c \ln \frac{\vartheta - \vartheta_{\infty}}{\vartheta_0 - \vartheta_{\infty}}.$$
 (6)

The calculation of the time then depends on the one hand on how the Nusselt number and thus the heat transfer coefficient is defined, and on the other hand on how the ratio V/A is defined. If only one characteristic dimension is used, the volume to surface ratio V/A is set to

$$\frac{V}{A} = \frac{d_{\rm ch}}{6} \tag{7}$$

as for the sphere. In accordance with its definition, Eq. (7) is only exactly satisfied for the Sauter diameter. Therefore, a corrected heat transfer coefficient α_t is introduced, which adjusts the error in the other charac-

teristic dimensions, so that the time t, in accordance with Eq. (6), is correctly calculated. The Nusselt number belonging to it is defined in accordance with

$$Nu_t = \frac{\alpha_t d_{\rm ch}}{\lambda}.$$
(8)

From this the calculation equation for the heating time results

$$t = \frac{d_{\rm ch}}{6\alpha_t} \rho c \ln \frac{\vartheta - \vartheta_\infty}{\vartheta_0 - \vartheta_\infty} = \frac{d_{\rm ch}^2}{6\lambda N u_t} \rho c \ln \frac{\vartheta - \vartheta_\infty}{\vartheta_0 - \vartheta_\infty}.$$
 (9)

Owing to

$$\frac{V}{\alpha A} = \frac{d_{\rm ch}}{6\alpha_t},\tag{10}$$

the following ensues for the determination equation for Nu_t :

$$Nu_t = \frac{d_{\rm ch}^2}{6V} \frac{A\alpha}{\lambda}.$$
 (11)

Using the shape coefficient corresponding with Table 1 and the spheroid volume

$$V = \frac{4}{3}\pi d^2 L,\tag{12}$$

this Nusselt number can be analytically calculated for the spheroid. In Fig. 3 these new Nusselt numbers Nu_i , resulting from the various characteristic dimensions, are plotted as a function of L/d. A strong dependence on the ratio L/d and a large deviation from the value 2 of the sphere for $L/d \neq 1$ is apparent. If the sieve diameter dis used as characteristic dimension, a deviation in the calculation of the heating time between the real value



Fig. 3. Nusselt number $Nu_t(d_{ch})$ for calculating the heating time when applying the same characteristic dimension d_{ch} to Nu_t and to the specific surface area.

and the value using Nu = 2 can be detected. For example, this deviation is of approximately a factor of 2 for a slim particle with L/d = 3.5 and of approximately a factor of 2.5 for a flat particle with L/d = 0.3. Since the ratio L/d is usually unknown, the Nusselt number thus cannot be determined if only one single characteristic dimension is known. The heat transfer for a number of model particles was therefore numerically calculated to determine suitable characteristic dimensions for different particle shapes.

4. Model bodies

A very large fluid volume must be assumed to approximate the "infinite" extent of the surroundings. In the numerical calculation this results in a large number of volume elements, which have a sizable storage requirement and need long computation times. For that reason, only axisymmetric bodies, which can be calculated two dimensionally, were selected.

The following were used as model bodies (Fig. 4):

- cylinder with axial ratio of $0.2 \leq L/d \leq 5$;
- spheroid with axial ratio of $0.2 \leq L/d \leq 5$;
- double cone with axial ratio of $0.2 \leq L/d \leq 5$;
- barrel with axial ratio of $0.2 \leq L/d \leq 5$;
- dumbbell-shaped body with axial ratio of $1 \le L/d \le 5$;
- spheroid with wavy surface.

Two lengths, d and L, are needed for the description of the first three bodies; three quantities are already required in the case of the barrel and the dumbbell-shaped body (L, d, d_2) ; and four quantities are finally necessary for the spheroid with wavy surface (L, d, amplitude t ofthe sine oscillation and the number of waves N).

5. Numerical determination of the minimum Nusselt number

The minimum heat flow can be calculated from the steady-state temperature field around the body. The following differential equation applies to this:

$$\frac{\partial}{\partial x} \left(\lambda \frac{\partial \vartheta}{\partial x} \right) + \frac{\partial}{\partial y} \left(\lambda \frac{\partial \vartheta}{\partial y} \right) = 0.$$
(13)

As boundary conditions, ϑ_W and ϑ_∞ are assumed to be constant. The dimensionless temperature Θ is introduced and dimensionless spatial coordinates X and Y are formulated with a characteristic diameter d_{ch} . The thermal conductivity λ is assumed to be constant.

The following is then valid for the total heat flow \dot{Q} :

$$\dot{Q} = \int_{A} \dot{q} \, \mathrm{d}\vec{A} = -\int_{A} \lambda \operatorname{grad} \vartheta \, \mathrm{d}\vec{A}. \tag{14}$$

In accordance with Newton's law of cooling, the heat transfer coefficient α is defined as

$$\dot{Q} = \alpha A(\vartheta_{\rm W} - \vartheta_{\infty}).$$
 (15)

From equations (14) and (15)

$$\frac{\alpha A}{\lambda} = -\int_{A} \operatorname{grad} \Theta \, \mathrm{d}\vec{A} \tag{16}$$

follows for the shape coefficient. To solve the differential equation, a finite volume procedure was employed on structured orthogonal grids, allowing the calculation of the heat flow for pure heat conduction. A modified version of the volume method proposed by Nirschl [6] was applied. Assuming a given surface structure with free extension into the surrounding environment, a hyperbolic grid generation is well suited for producing orthogonal grids. Fig. 5 shows such a hyperbolic grid



Fig. 4. Basic shapes of the model particles.



Fig. 5. A grid around a cylinder produced with a hyperbolic grid generator.

around a cylinder. Sharp edges had to be smoothed in order to avoid oscillations of the solution of the grid generator. The outer contour of the grid is approximately at $d_a = 40d$.

The analytical solution for the spheroid [4] was employed to check the numerical error when calculating the temperature field. A maximum discretization error of approximately 4% results for the numerically calculated area. The error, which results from grid generation only up to fortyfold of the outer radius of the body, is not taken into account here. If this error is added, a total error of a maximum of 11% results. This error can be reduced by not introducing $\Theta_{\infty} = 0$ as the boundary condition on the outer edge but rather the value of $\Theta_{\infty} = 0.025$, resulting from the analytical solution of the sphere at $d_a = 40d$.

6. Comparison of the Nusselt numbers for various bodies

To investigate the influence of the body shape on the Nusselt number Nu_t , the values according to Eq. (11) were compared for the different bodies in Fig. 6. The characteristic dimension is set as $d_{ch} = d$. A large devia-



Fig. 6. Nusselt number Nu_t with d as characteristic dimension.

tion appears amongst the different body shapes. Also a large deviation from the value Nu = 2 of the sphere can be seen for all body shapes. Therefore, the text below discusses possibilities to achieve a formulation for the Nusselt number which is as independent as possible from the body shape. In accordance with Fig. 3, using $d_{\rm V}$ or $d_{\rm S}$ as characteristic dimensions for Nu_t , the smallest deviations from the value Nu = 2 resulted. For that reason the Nusselt numbers for all model bodies, formed using $d_{\rm V}$ and $d_{\rm S}$, are compared in Fig. 7. A relatively low dependence on the body shape for $d_{\rm V}$ appears and a somewhat larger dependence for $d_{\rm S}$. The influence of L/dhowever cannot yet be disregarded in these two characteristic dimensions. Thus, no uniform Nusselt number can be specified for the different body shapes using only one characteristic dimension. The text below investigates whether this is possible using two characteristic dimensions. As Fig. 3 shows, the largest independence from L/d is achieved for the definition of the Nusselt number



Fig. 7. Nusselt number Nu_t for d_V and d_S as characteristic dimension.

using Eq. (3) with $d_{ch} = d_A$. Fig. 8 shows this Nusselt number for the model bodies. To calculate the heating time exactly, it is additionally necessary to know the real ratio $V/A = d_S/6$ of the particle. The dependence on the body shape can then be disregarded and the deviation from the value 2 of the sphere amounts to only a maximum of 15%. The value 2 of the sphere can thus still be used. However the two new characteristic dimensions d_S and d_A are necessary. But especially d_A is metrologically difficult to determine. Metrologically easiest to determine are d (e.g. through sieving) and d_s (e.g. through BET). Hence, a presentation of the Nusselt number independent of the body shape was investigated using both these dimensions. To this end the Nusselt number Nu_t was formed, in accordance with Eq. (11) using the diameter d. The resulting Nusselt numbers are plotted against the ratio d_s/d in Fig. 9. It is apparent that the values for the various bodies now lie very close to each other. Only in the range of $d_s/d > 1$ does the double cone show a



Fig. 8. Nusselt number for d_A as characteristic dimension and usage of the real ratio of V/A of the particle.



Fig. 9. Nusselt number Nu_t for d as characteristic dimension.



Fig. 10. Nusselt number for d_A as characteristic dimension and usage of the real ratio of V/A of the particle.

Table 2												
Curve parameters for Figs. 10 and 11												
Curve	1	2	3	4	5	6	7	8	9	10	11	12
N	0	10	10	8	8	8	6	6	6	4	4	4
$t/d \ (L/d > 1)$	0	0.025	0.05	0.025	0.05	0.1	0.025	0.05	0.1	0.025	0.05	0.1
t/L (L/d < 1)												



Fig. 11. Nusselt number Nu_t for d as characteristic dimension.

somewhat larger deviation from the other curves. If the data points for all calculated bodies are approximated by an exponential function, the following equation results:

$$Nu_t = 1.80 \,\mathrm{e}^{-2.22(d_{\mathrm{S}}/d-1)}.$$
(17)

With knowledge of d_s and d, the heating time in accordance with Eq. (9) (with $d_{ch} = d$) can thus be calcu-

lated relatively exactly using this Nusselt number. By applying the corrected Nusselt number, it is then unnecessary to know the surface area of the individual particle.

7. Influence of surface waviness

Until now only smooth body shapes were considered in model particles. A sine function was therefore superimposed on the surface contour of the spheroid to approximate surface waviness. In this way a waviness of the surface is achieved as Fig. 4 represents in an example. Besides L and d, the amplitude of the sine function and the number N of the waves are added as additional body dimensions. The number of sine oscillations was varied between N=4 and N=10 and the amplitude related to the smallest dimension was varied between 0.025 and 0.1. Greater values for N and t were impossible since a limit was set by the hyperbolic grid generator, because above all this is suitable for convex surfaces.

Analogous to Fig. 8 the Nusselt number, formed with d_A , is represented in Fig. 10 as a function of L/d. Parameters are N and t in accordance with Table 2. The influence of these parameters grows all the smaller, the more L/d deviates from the value 1. With -5% to +15%, the differences from the value 2 of the sphere are again

relatively small. Analogous to Fig. 9 the newly defined Nusselt number Nu_t , formed with d, is represented in Fig. 11 as a function of d_S/d and with the parameters from Table 2. Again a relatively small deviation from the regression curve in Fig. 9 results. Therefore the heat transfer of various particle shapes can be uniformly represented, if d is applied as characteristic diameter both to the Nusselt number and to V/A, and Nu_t is calculated as a function of d/d_S in accordance with Eq. (17).

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